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IN THE CLAIMS

Please amend the claims as shown below.

1. (Currently amended) A time-to-contact estimate determination system for generating an estimate as to the time-to-contact of a vehicle moving along a roadway with an obstacle comprising:
 - A. an image receiver configured to receive image information relating to a series of at least two images as the vehicle moves along a roadway; and characterized by
 - B. a processor configured to determine a scaling factor that defines a ratio between a dimension length associated with two features of the obstacle in a first one of the at least two images and the same dimension-length between the same two features of the obstacle in a second one of the at least two images and uses the ratio to generate a time-to-contact estimate of the vehicle with the obstacle.
2. (Previously presented) A system according to claim 1 wherein the scaling factor defines a ratio between vertical dimensions of the obstacle in the images and uses the ratio to estimate the time-to-contact.
3. (Previously presented) A system according to claim 1 wherein the scaling factor defines a ratio between horizontal dimensions of the obstacle in the images and uses the ratio to estimate the time-to-contact.
4. (Previously presented) A system according to claim 1 wherein the at least two images comprises more than two images.
5. (Previously presented) A system according to claim 4 wherein the processor processes the image information to determine a lateral displacement of the object relative to a position of the vehicle.
6. (Currently amended) A system according to ~~[[claim]]~~ claim 5 wherein the processor determines a likelihood of collision responsive to whether or not the lateral displacement

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substantially uniformly approaches zero.

~~a ratio between a dimension of the obstacle in a first one of the at least one image and the same dimension of the obstacle in a second one of the at least one image~~

7. (Previously presented) A system according to claim 1 wherein the processor generates a time-to-contact T in accordance with the expression $T = [1/(S-1)]\Delta T$ where S is the scaling factor and ΔT is a time lapse between two images of the at least two images.